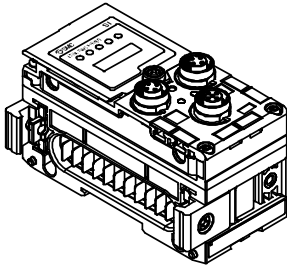




ORIGINAL INSTRUCTIONS

Instruction Manual  
Fieldbus device - SI unit for EtherNet/IP™  
IO-Link compatible  
EX600-SEN3-X80 series



The intended use of this product is to control pneumatic valves and I/O while connected to the IO-Link protocol.

1 Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of “Caution,” “Warning” or “Danger.” They are all important notes for safety and must be followed in addition to International Standards (ISO/IEC)\*<sup>1)</sup>, and other safety regulations.

<sup>1)</sup>ISO 4414: Pneumatic fluid power — General rules and safety requirements for systems and their components.  
ISO 4413: Hydraulic fluid power — General rules and safety requirements for systems and their components  
IEC 60204-1: Safety of machinery - Electrical equipment of machines - Part 1: General requirements  
ISO 10218-1: Robotics — Safety requirements — Part 1: Industrial robots

- Refer to product catalogue, Operation Manual and Handling Precautions for SMC Products for additional information.
- Keep this manual in a safe place for future reference.

	<b>Danger</b>	Danger indicates a hazard with a high level of risk which, if not avoided, will result in death or serious injury.
	<b>Warning</b>	Warning indicates a hazard with a medium level of risk which, if not avoided, could result in death or serious injury.
	<b>Caution</b>	Caution indicates a hazard with a low level of risk which, if not avoided, could result in minor or moderate injury.



Warning

- **Always ensure compliance with relevant safety laws and standards.**
- All work must be carried out in a safe manner by a qualified person in compliance with applicable national regulations.

2 Specifications

The EX600 range of units can be connected to a fieldbus to realize the reduction of input or output device wiring and a distributed control system. The system communicates with the fieldbus through the SI unit.

One SI unit can be connected to manifold valves with up to 32 outputs, and to input, output, I/O and IO-Link master units to a maximum of 10 units. The maximum number of connected IO-Link master units is 4.

2.1 General specifications

Item	Specifications
Ambient temperature	−10 to +50 °C
Ambient humidity	35 to 85%RH (No condensate)
Ambient storage temperature	−20 to +60 °C
Withstand voltage	500 VAC applied for 1 minute
Insulation resistance	500 VDC, 10 MΩ or more
Enclosure rating	IP67 (manifold assembled)
Weight	300 g

2 Specifications (continued)

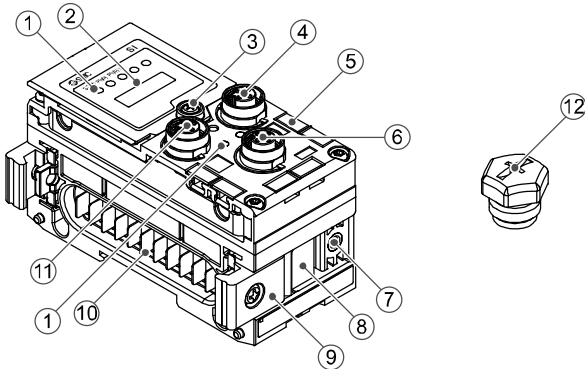
2.2 Electrical specifications

	Item	Specifications
Power supply voltage range / current consumption	Control and Input power supply	24.0 VDC 2.0 A max.
	Solenoid valve and Output power supply	24.0 VDC 2.0 A max.
	Internal current consumption	120 mA maximum
Solenoid valve specification	Output type	PNP / source (negative common)
	Number of outputs	32 outputs
	Applicable valve series	24 VDC and 1.0 W max. Solenoid valve with surge voltage suppression (manufactured by SMC)
	Output condition during communication error	HOLD / CLEAR / Force ON
	Protection function	Short circuit protection

2.3 Communication specifications

Item	Specifications
Protocol	EtherNet/IP™ (conformance version: Composite11)
Communication medium	Standard EtherNet cable (CAT5 or more, 100BASE-TX)
Communication speed	10 / 100 Mbps
Communication type	Full duplex / Half duplex
IP address setting range	Setting by switch: 192.168.0 or 1.1 to 254 By DHCP server: arbitrary address
Device information	Vendor ID: 7 (SMC Corporation) Device type: 12 (communication adapter) Product code: 203
Network Topology	Star, Linear Bus and Ring (including DLR)
EtherNet/IP QuickConnect™	Supported
Web server	Supported

3 Name and function of Individual parts



No	Part	Description
1	LED display	Displays the SI unit status.
2	Display cover	Display cover for switch setting.
3	Display cover screw	To open the display cover.
4	Connector (BUS OUT)	Connector for Fieldbus Outputs.
5	Marker groove	Groove for identification marker.
6	Connector (PCI)	Connector for Handheld terminal.
7	Valve plate hole	Hole for valve plate mounting.
8	Valve plate groove	Groove for valve plate mounting.
9	Joint bracket	Bracket for joining to adjacent units.
10	Unit connector	Connector for signal/power to next unit.
11	Connector (BUS IN)	Connector for Fieldbus Inputs.
12	Seal cap (2 pcs.)	For all unused M12 connectors

4 Assembly

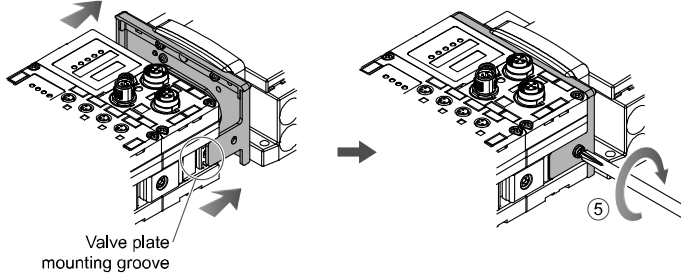
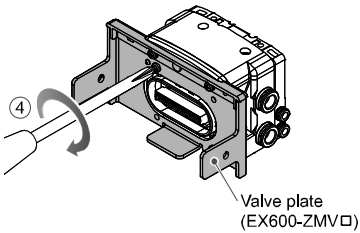
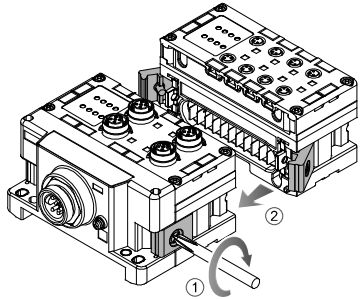
4.1 Assembling the unit



Warning

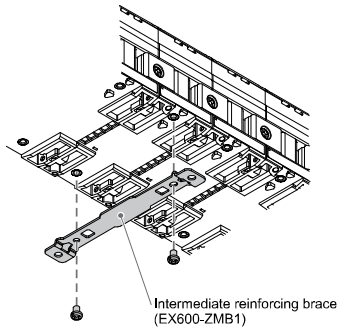
Do not install the product unless the safety instructions have been read and understood.

- (1) Connect an I/O unit to the end plate. Digital and analogue units can be connected in any order. Joint bracket screw tightening torque: 1.5 to 1.6 N•m.
- (2) Add more I/O units. Up to 9 I/O units can be connected to one manifold.
- (3) Connect the SI unit. After connecting the required I/O units, connect the SI unit. The connection method is as above.
- (4) Mount the valve plate (EX600-ZMV#) to the valve manifold using the valve screws (M3 x 8) supplied. (Tightening torque: 0.6 to 0.7 N•m).
- (5) Connect the SI unit assembly to the valve manifold. Insert the valve plate into the valve plate mounting groove. Then fix using the valve plate mounting screws (M4 x 6) supplied (Tightening torque: 0.7 to 0.8 N•m).



5 Installation

- Do not expose to direct sunlight. Use a suitable protective cover.
  - Do not install in a location subject to vibration or impact in excess of the product's specifications.
  - Do not mount in a location exposed to radiant heat that would result in temperatures in excess of the product's specifications.
- **Direct mounting**  
(1) When assembling six or more units, the middle part of the assembly must be fitted with an intermediate reinforcing brace (EX600-ZMB1) before mounting using 2-M4 x 5 screws (Tightening torque: 0.7 to 0.8 N•m).

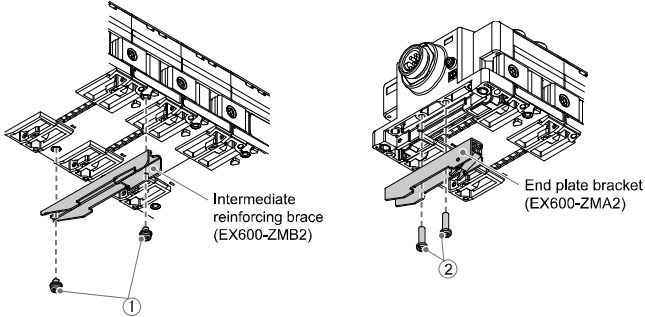


- (2) Mount and tighten the end plate at one end of the unit and mount the intermediate reinforcing brace if required using M4 screws (Tightening torque: 0.7 to 0.8 N•m). Fix the end plate at the valve side while referring to the operation manual for the applicable valve series.

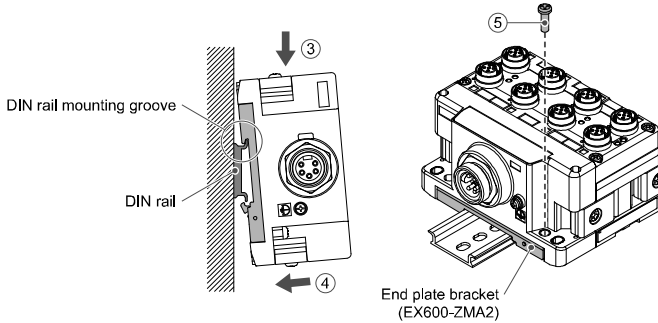
5 Installation (continued)

• DIN rail mounting

- (1) When assembling six or more units, the middle part of the complete assembly must be fitted with an intermediate reinforcing brace for DIN rail mounting (EX600-ZMB2), using 2-M4 x 6 screws. (Tightening torque: 0.7 to 0.8 N•m).
- (2) Mount the end plate bracket (EX600-ZMA2) to the end plate using 2-M4 x 14 screws (Tightening torque: 0.7 to 0.8 N•m). For the SY series, use end plate bracket (EX600-ZMA3).



- (3) Hook the DIN rail mounting groove on to the DIN rail.
- (4) Press the manifold using its side hooked to the DIN rail as a fulcrum until the manifold is locked onto the DIN rail.
- (5) Fix the manifold by tightening the DIN rail fixing screws (M4 x 20) on the end plate bracket (Tightening torque: 0.7 to 0.8 N•m). Refer to the Operation Manual for the applicable valve series on the SMC website (URL: <https://www.smcworld.com>) for the mounting method of the valve manifold.



5.1 Wiring connections

• Communication Connector

Select the appropriate cables to mate with the connectors on the SI unit. The EtherNet/IP™ connection port pin layout is as shown below.

Connector	Pin No.	Signal name
BUS IN / BUS OUT	1	TX+
	2	RX+
	3	TX-
	4	RX-

• Power Supply Connector

The system is operated using power supplied from the EX600-ED# end plate. Refer to the end plate instruction manual and operation manual for the power supply connection details.

The M12 connector cable for fieldbus and power supply connections has two types, Standard M12 and SPEEDCON compatible. If both plug and socket have SPEEDCON connectors, the cable can be inserted and connected by turning it a 1/2 rotation. A standard connector can be connected to a SPEEDCON connector.



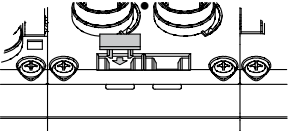
Warning

- Be sure to fit a seal cap (EX9-AWTS) on any unused connectors. Proper use of the seal cap enables the enclosure to maintain IP67 specification.

5 Installation (continued)

5.2 Identification marker

The signal name of the input or output devices and unit address can be written on the marker and can be installed on each unit.  
Mount a marker (EX600-ZT1) into the marker groove as required.



5.3 Environment

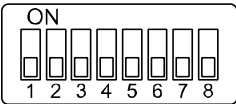
Warning

- Do not use in an environment where corrosive gases, chemicals, salt water or steam are present.
- Do not install in a location subject to vibration or impact in excess of the product's specifications.
- Do not mount in a location exposed to radiant heat that would result in temperatures in excess of the product's specifications.

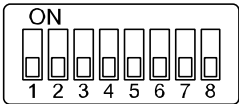
6 Settings

6.1 Switch Settings

- Open the display cover.
- Turn OFF the power before setting the switches.
- Set the switches using a small flat blade screwdriver, referring to the information below.
- After setting the switches close the cover and tighten the screw (Tightening torque: 0.3 to 0.4 N•m).
- When the power supply is turned ON the switch setting will become effective.



Settings1



Settings2

Hold / Clear setting

Set the output status for when the fieldbus has a communication error or is in an idle state.

Settings1	Content
1	
OFF	Output is OFF (default setting)
ON	Hold the Output

Diagnostics setting

Allocates the diagnostic data to the input data.

Settings1	Mode	Content	Diagnostic size for Input
2			
OFF	0	Input data only (default setting)	0 byte
ON	1	Input data + System diagnostics + Unit diagnostics	4 bytes

IP address setting

Set the IP address of the SI unit.

Settings1	Settings2								IP Address
8	1	2	3	4	5	6	7	8	
OFF	ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	192.168.0.1
OFF	OFF	ON	OFF	OFF	OFF	OFF	OFF	OFF	192.168.0.2
:	:	:	:	:	:	:	:	:	:
OFF	ON	OFF	ON	ON	ON	ON	ON	ON	192.168.0.253
OFF	OFF	ON	ON	ON	ON	ON	ON	ON	192.168.0.254
ON	ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	192.168.1.1
ON	OFF	ON	OFF	OFF	OFF	OFF	OFF	OFF	192.168.1.2
:	:	:	:	:	:	:	:	:	:
ON	ON	OFF	ON	ON	ON	ON	ON	ON	192.168.1.253
ON	OFF	ON	ON	ON	ON	ON	ON	ON	192.168.1.254
ON/OFF	ON	ON	ON	ON	ON	ON	ON	ON	DHCP mode
ON/OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	Remote control mode

6 Settings (continued)

- DHCP mode is the mode to obtain IP address from DHCP server. Obtained IP address is lost when the power supply is cut.
- Remote control mode is the mode to respond to commands via the BOOTP/DHCP server provided by Rockwell Automation. Refer to the BOOTP/DHCP server manual for further details.
- Settings1 switch number 3 to 7 are not used and should remain OFF.

Refer to the operation manual on the SMC website (URL: <https://www.smcworld.com>) for further information on switch settings.

6.2 Configuration

Technical documentation giving detailed configuration information can be found on the SMC website (URL: <https://www.smcworld.com>).

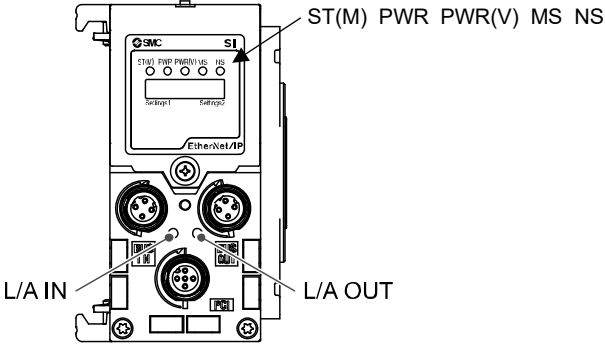
7 How to Order

Refer to the operation manual on the SMC website (URL: <https://www.smcworld.com>) for How to order information.

8 Outline Dimensions (mm)

Refer to the operation manual on the SMC website (URL: <https://www.smcworld.com>) for outline dimensions.

9 LED Display



Display	Content
ST(M)	Displays the diagnostic status of the unit.
PWR	Displays the status of the power supply voltage for control and input.
PWR(V)	Displays the status of the power supply voltage for output.
MS	Displays the module status.
NS	Displays the network status.
L/A IN	Displays the communication status of the BUS IN.
L/A OUT	Displays the communication status of the BUS OUT.

9 LED Display (continued)

9.1 SI unit status

LED	LED Colour	Operation
ST(M)	OFF	The power supply for control and input is OFF.
	Green ON	Normal operation.
	Green flashing	Diagnostic error in I/O unit detected.
	Red flashing	One of the following diagnostic error detected (when diagnostics is enabled). •Valve ON/OFF counter exceeded the set value. •Valve is short circuited or disconnected.
	Red/Green flashing	Communication error detected between SI unit and I/O unit.
	Red ON	SI unit has failed.
PWR	Green ON	The power supply voltage for control and input is normal.
	Red ON	The power supply voltage for control and input is out of range (when diagnostics is enabled).
PWR(V)	OFF	The power supply voltage for output is OFF or out of range (when diagnostics is disabled).
	Green ON	The power supply voltage for output is normal.
	Red ON	The power supply voltage for output is OFF or out of range (when diagnostics is enabled).
MS	Green flashing	Either of the following conditions are detected: •The unit has not been configured correctly. •The master is in idle state.
	Green ON	Normal operation.
	Red flashing	Diagnostics error detected.
	Red ON	SI unit has failed.
NS	OFF	IP address is not set.
	Green flashing	EtherNet/IP™ communication is not established.
	Green ON	EtherNet/IP™ communication is established.
	Red flashing	EtherNet/IP™ communication time out.
	Red ON	IP address is duplicated.

9.2 Communication status

		Content
L/A IN	OFF	Bus IN: No Link, No Activity
	Green ON	Bus IN: Link, No Activity (100 Mbps)
	Green flashing	Bus IN: Link, Activity (100 Mbps)
	Yellow ON	Bus IN: Link, No Activity (10 Mbps)
	Yellow flashing	Bus IN: Link, Activity (10 Mbps)
L/A OUT	OFF	Bus OUT: No Link, No Activity
	Green ON	Bus OUT: Link, No Activity (100 Mbps)
	Green flashing	Bus OUT: Link, Activity (100 Mbps)
	Yellow ON	Bus OUT: Link, No Activity (10 Mbps)
	Yellow flashing	Bus OUT: Link, Activity (10 Mbps)

10 Maintenance

10.1 General Maintenance

Caution

- Not following proper maintenance procedures could cause the product to malfunction and lead to equipment damage.
- If handled improperly, compressed air can be dangerous.
- Maintenance of pneumatic systems should be performed only by qualified personnel.
- Before performing maintenance, turn off the power supply and be sure to cut off the supply pressure. Confirm that the air is released to atmosphere.
- After installation and maintenance, apply operating pressure and power to the equipment and perform appropriate functional and leakage tests to make sure the equipment is installed correctly.
- If any electrical connections are disturbed during maintenance, ensure they are reconnected correctly and safety checks are carried out as required to ensure continued compliance with applicable national regulations.
- Do not make any modification to the product.
- Do not disassemble the product, unless required by installation or maintenance instructions
- Stop operation if the product does not function correctly.

11 Limitations of Use

11.1 Limited warranty and Disclaimer/Compliance Requirements

Refer to Handling Precautions for SMC Products.

12 Product disposal

This product should not be disposed of as municipal waste. Check your local regulations and guidelines to dispose of this product correctly, in order to reduce the impact on human health and the environment.

13 Contacts

Refer to [www.smcworld.com](http://www.smcworld.com) or [www.smc.eu](http://www.smc.eu) for your local distributor / importer.

SMC Corporation

URL : <https://www.smcworld.com> (Global) <https://www.smc.eu> (Europe)  
SMC Corporation, 1-5-5, Kyobashi, Chuo-ku, Tokyo 104-0031, JAPAN  
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Template DKP50047-F-0850